

The diagram illustrates a multi-channel recording system with five traces:

- RF**: A trace showing a single pulse.
- GSS**: A trace showing a step function, transitioning from a lower level to a higher level.
- GpE**: A trace showing a rectangular pulse, indicated by a shaded box.
- Gp**: A trace showing a complex waveform with segments labeled $-G$, z , and $2z$. Time points t_1 and t_2 are marked on the x-axis.
- G**: A trace showing a complex waveform with segments labeled z and $2z$. Time points t_1 , t_2 , and t_3 are marked on the x-axis.

Flow along read direction only

$$x(t) = x_0 + v_x t$$

$$\phi = \gamma \int G_x(\pm) x dt \quad [\text{no flow case}]$$

$$\phi = \gamma \int G_n(t) x(t) dt$$

$$= \delta \int G_n(t) (x_0 + v_n t) dt$$

$$= \gamma \left[\int_{t_1}^{t_2} -G_x(x_0 + v_x t) dt + \int_{t_2}^t G_x(x_0 + v_x t) dt \right] \quad t_2 < t < t_3$$

$$= \delta \left[-G_x x_0 t \Big|_{t_1}^{t_2} + \left(-G_x V_x \frac{t^2}{2} \right) \Big|_{t_1}^{t_2} \right. \\ \left. + G_x x_0 t \Big|_{t_2}^t + \left(G_x V_x \frac{t^2}{2} \right) \Big|_{t_2}^t \right]$$

$$= \delta \left[-G_x x_0 (t_2 - t_1) - \frac{G_x V_x (t_2^2 - t_1^2)}{2} \right. \\ \left. + G_x x_0 (t - t_2) + \frac{G_x V_x (t^2 - t_2^2)}{2} \right]$$

$$= \gamma \left[-G_x x_0 (t_2 - t_1) - \frac{G_x V_x (t_2^2 - t_1^2)}{2} \right. \\ \left. + G_x x_0 (t - t_2) + \frac{G_x V_x (t^2 - t_2^2)}{2} \right]$$

writing this.

Relative to TE $\rightarrow t_1 + 2\tau$, coordinate change

$$t' = t - (t_1 + 2\tau)$$

$$= \gamma \left[-G_x x_0 \tau - \frac{G_x V_x (t_2^2 - t_1^2)}{2} \right. \\ \left. + G_x x_0 (t' + t_1 + 2\tau - t_2) \right. \\ \left. + \frac{G_x V_x (t'^2 + t_1^2 + 4\tau^2 + 4\tau t_1 + 2t' t_1 + 4t' \tau - t_2^2)}{2} \right]$$

$$= \delta \left[-G_x x_0 z - \frac{G_x V_x}{2} (t_2^2 - t_1^2) + G_x x_0 (t' - z + 2z) \right. \\ \left. + \frac{G_x V_x}{2} \left[t_1'^2 - (t_2^2 - t_1^2) + 4z(t_1 + z) + 2t'(t_1 + 2z) \right] \right]$$

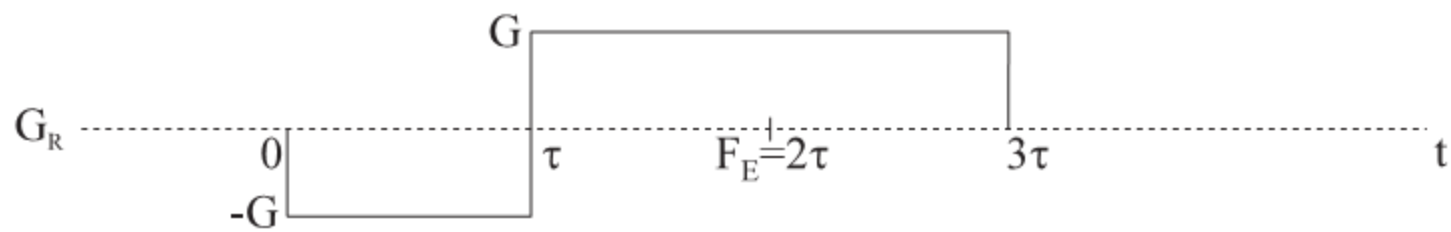
$$= \delta \left[G_x x_0 t' - G_x V_x (t_2^2 - t_1^2) + \frac{G_x V_x}{2} t_1'^2 \right. \\ \left. + \frac{G_x V_x}{2} \left[2z(t_1 + z) + t'(t_1 + 2z) \right] \right]$$

$$t_1 = 0 \text{ (origin shift)}$$

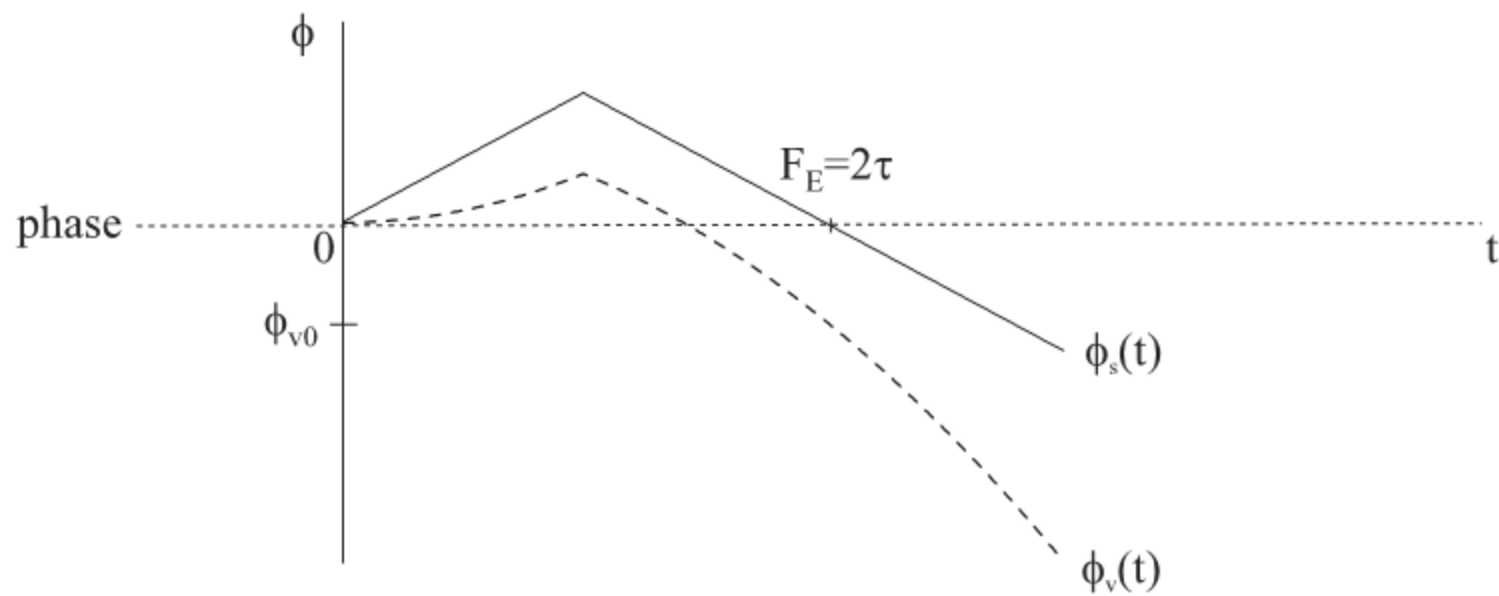
$$t_2 = z$$

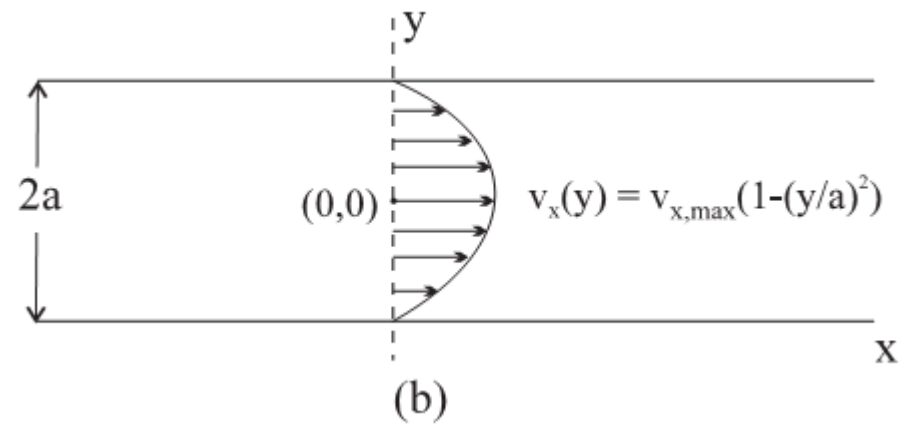
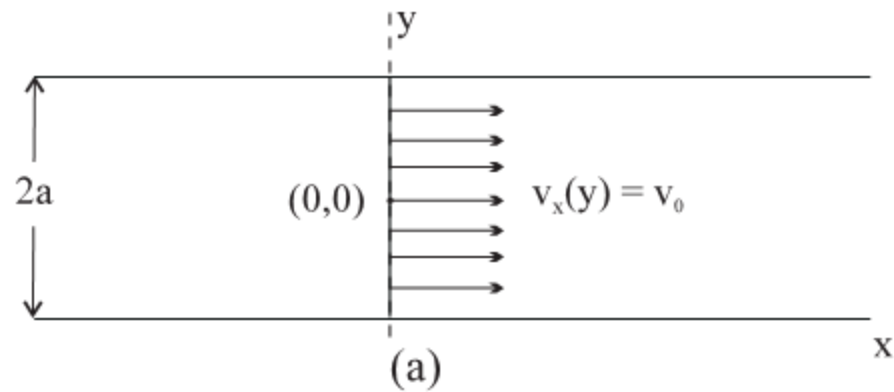
$$\Rightarrow \delta \left[G_x x_0 t' - G_x V_x z^2 + G_x V_x t_1'^2 + G_x V_x 2z^2 + G_x V_x t' 2z \right]$$

$$\phi = \underbrace{\delta G_x t' (x_0 + V_x 2z + V_x t')}_{\text{Additional phase terms}} + \delta G_x V_x z^2$$



(a)

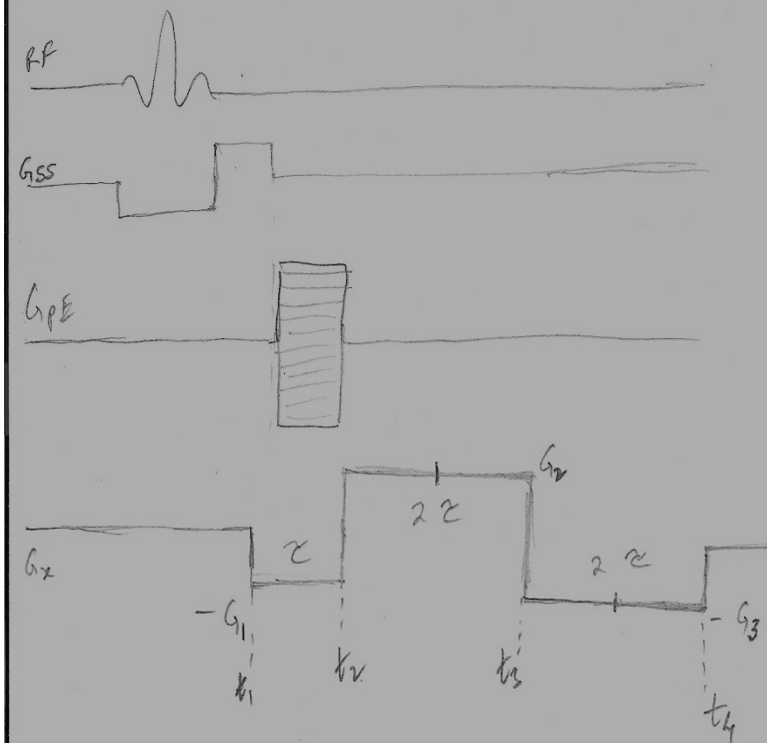




$$v_x(y) = v_{x,\max} \left(1 - \left(\frac{y}{a} \right)^2 \right)$$

$$v_x(y) = v_x(x_0, y_0) + \alpha(y - y_0)$$

$$\begin{aligned}
\hat{\rho}_v(x_0, y_0) &= \frac{\rho_0(x_0, y_0)}{\Delta y} \int_{y_0 - \Delta y/2}^{y_0 + \Delta y/2} dy e^{-i\gamma G v_x(x_0, y_0) \tau^2} e^{-i\gamma G \alpha (y - y_0) \tau^2} \\
&= \rho_0(x_0, y_0) e^{-i\gamma G v_x(x_0, y_0) \tau^2} \text{sinc}(\gamma \alpha G \tau^2 \Delta y / 2)
\end{aligned}$$



$$\begin{aligned}
 \phi &= \delta \left[\int G_x(t) (x_0 + v_x t) dt \right] \\
 &= \delta \left[\int_{t_1}^{t_2} -G_1 (x_0 + v_x t) dt + \int_{t_2}^{t_3} G_2 (x_0 + v_x t) dt + \int_{t_3}^t (-G_3) (x_0 + v_x t) dt \right] \\
 &= \delta \left[-G_1 x_0 (t_2 - t_1) - \frac{G_1 v_x}{2} (t_2^2 - t_1^2) \right. \\
 &\quad \left. + G_2 x_0 (t_3 - t_2) + \frac{G_2 v_x}{2} (t_3^2 - t_2^2) \right. \\
 &\quad \left. - G_3 x_0 (t - t_3) - G_3 v_x (t^2 - t_3^2) \right]
 \end{aligned}$$

$$\boxed{t_1=0, t_2=2, t_3=3} - \text{time origin shift}$$

$$= \int \left[-G_1 x_0 \tau - \frac{G_1 V_x \tau^2}{2} + G_2 x_0 2\tau + \frac{G_2 V_x 8\tau^2}{2} - G_3 x_0 (t-3\tau) - \frac{G_3 V_x}{2} (t^2 - 9\tau^2) \right]$$

time origin shift relative to TE $\Rightarrow \frac{4\tau}{\dots}$ $t' = t - 4\tau$

$$= \int \left[-G_1 x_0 \tau - \frac{G_1 V_x \tau^2}{2} + G_2 x_0 2\tau + \frac{G_2 V_x 8\tau^2}{2} - G_3 x_0 (t' + 4\tau - 3\tau) - \frac{G_3 V_x}{2} (t'^2 + 16\tau^2 + 8t'\tau - 9\tau^2) \right]$$

$$\begin{aligned}
 \phi &= \gamma \left[-G_1 x_0 z - \frac{G_1 V_x}{2} z^2 \right. \\
 &\quad + G_2 x_0 2z + \frac{G_2 V_x}{2} 8z^2 \\
 &\quad - G_3 x_0 z - \frac{G_3 V_x}{2} 16z^2 + \frac{G_3 V_x}{2} 9z^2 \\
 &\quad \left. - G_3 x_0 t' - \frac{G_3 V_x}{2} t'^2 - \frac{G_3 V_x}{2} 8t'z \right]
 \end{aligned}$$

For stationary spins, $V_x = 0$

For echo to happen, $\phi = 0$ @ $t' = 0$

$$\therefore \phi = 0 = \gamma x_0 z [-G_1 + 2G_2 - G_3]$$

$$\Rightarrow \underline{2G_2 = G_1 + G_3} \quad - \text{condition ①}$$

For moving spring, again, for the echo to occur @ $t'=0$, $\phi_v=0$

$$\phi_v = 0 = -\frac{G_1 v_x x^2}{2} + \frac{G_2 v_x 8x^2}{2} - \frac{G_3 v_x 16x^2}{2} + \frac{G_3 v_x 9x^2}{2}$$

$$\Rightarrow 8G_2 - G_1 - 7G_3 = 0$$

$$8G_2 = G_1 + 7G_3$$

$$4G_1 + 4G_3 = G_1 + 7G_3$$

$$G_1 = G_3$$

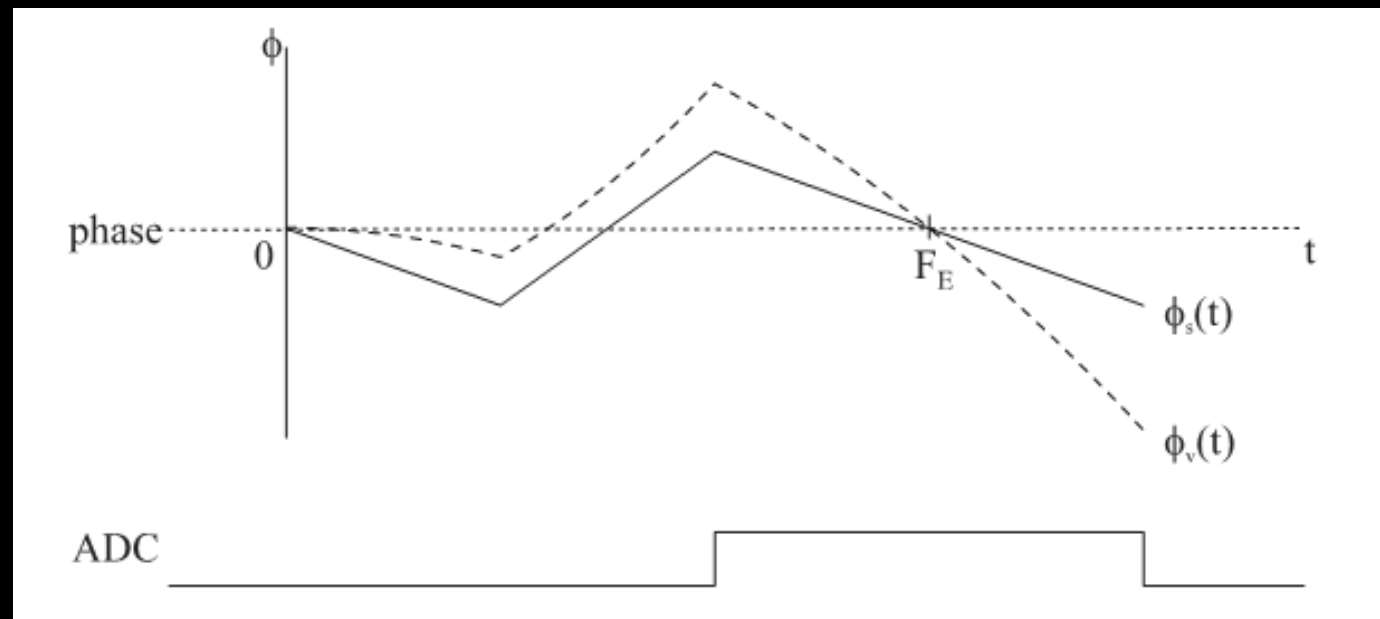
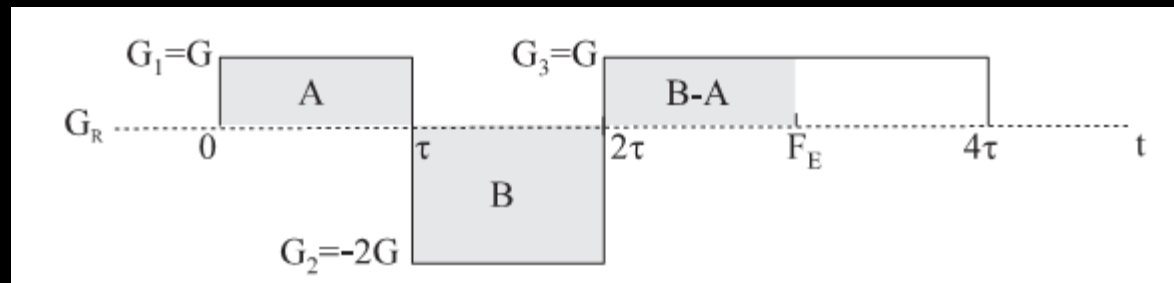
Substituting condition ①.

$$\therefore 2G_2 = G_1 + G_3$$

$$\Rightarrow \underline{G_1 = G_3 = G_2}$$

$$\phi_x(t) = -8Gx_0 t' - \frac{Gv_x}{2} t'^2 - \frac{Gv_x}{2} 8t'x$$

$$= -8Gt' \left[x_0 + 4v_x x + \frac{v_x}{2} t' \right]$$



$$G_1\tau + G_2\tau + G\tau = 0$$

i.e.,

$$G_1 + G_2 + G = 0$$

and

$$\frac{1}{2}G_1\tau^2 + \frac{1}{2}G_2(4\tau^2 - \tau^2) + \frac{1}{2}G(9\tau^2 - 4\tau^2) = 0$$

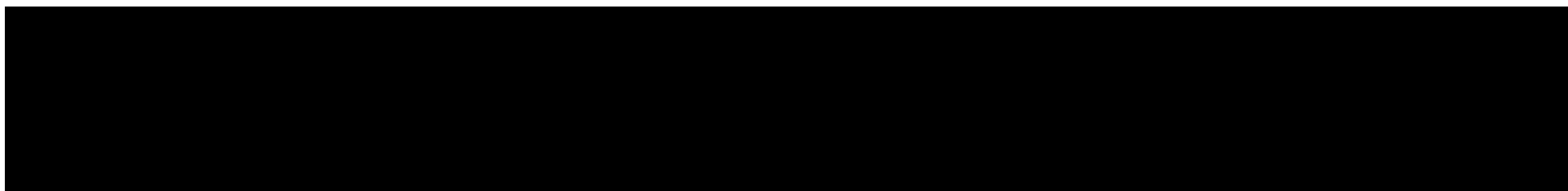
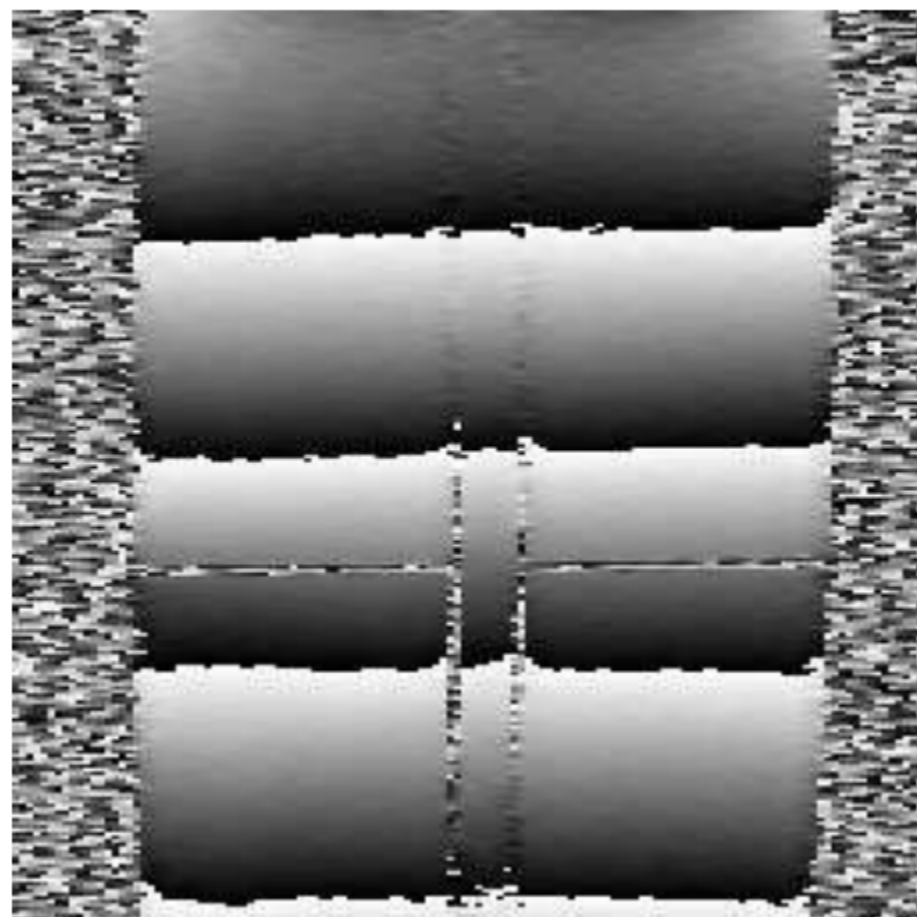
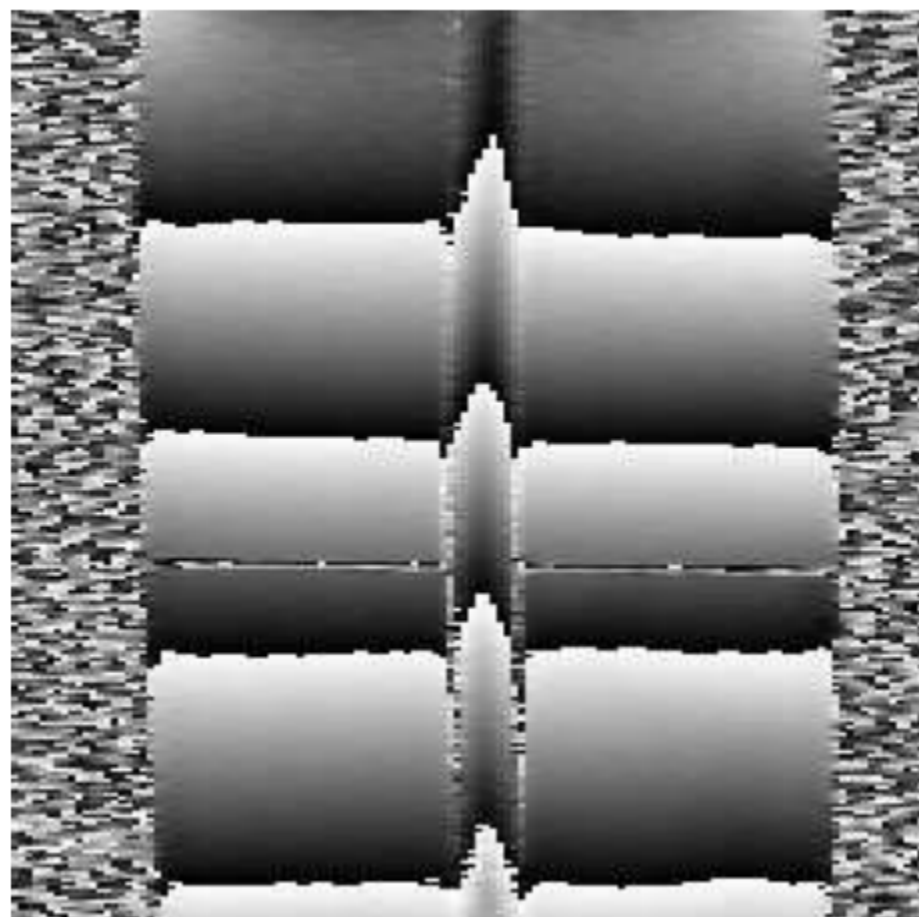
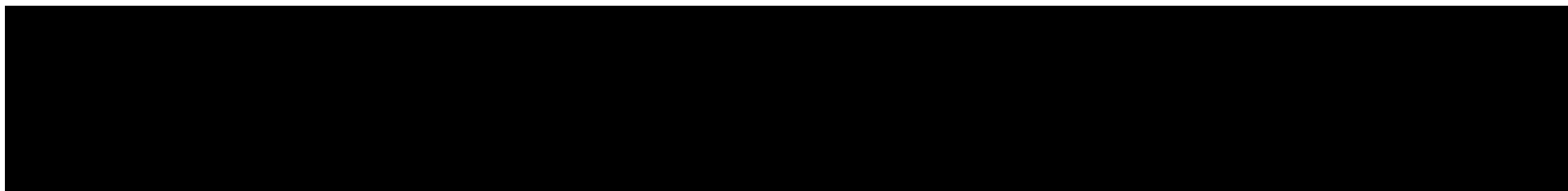
or

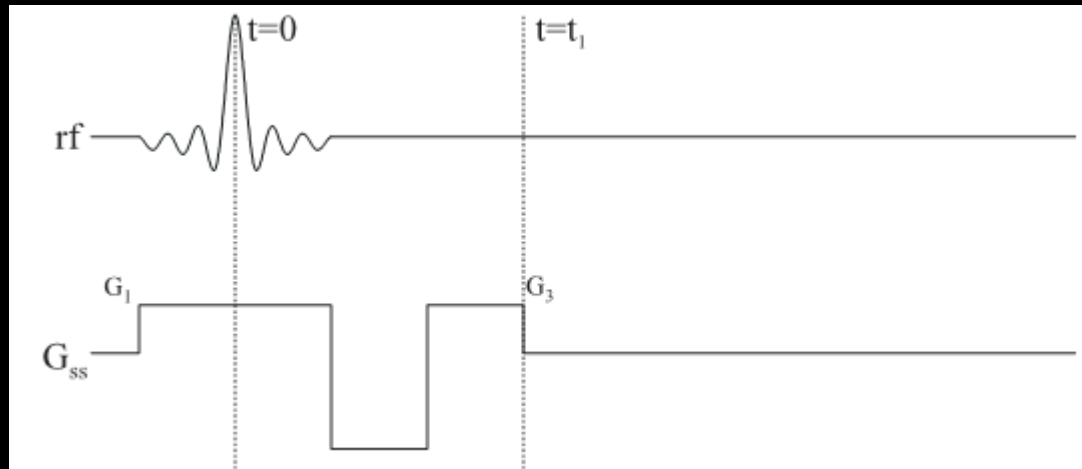
$$G_1 + 3G_2 + 5G = 0$$

Solving these equations yields

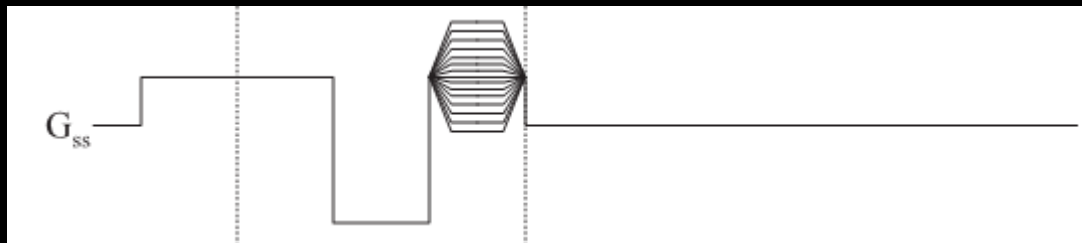
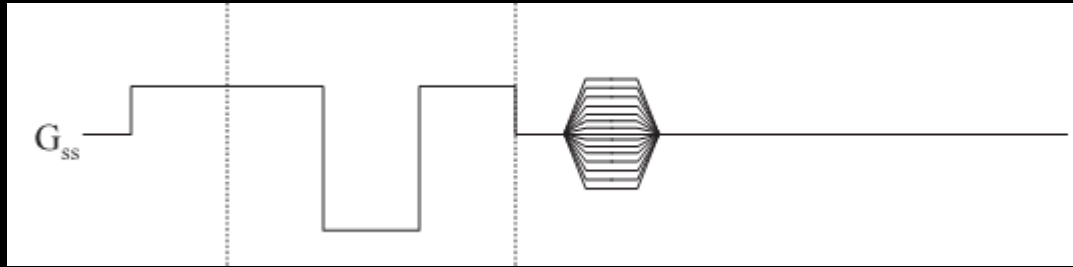
$$G_1 = -G \quad \text{and}$$

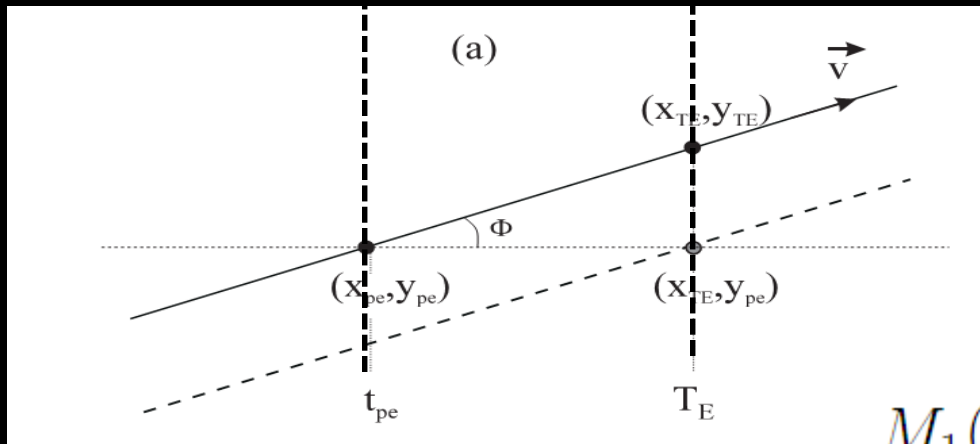
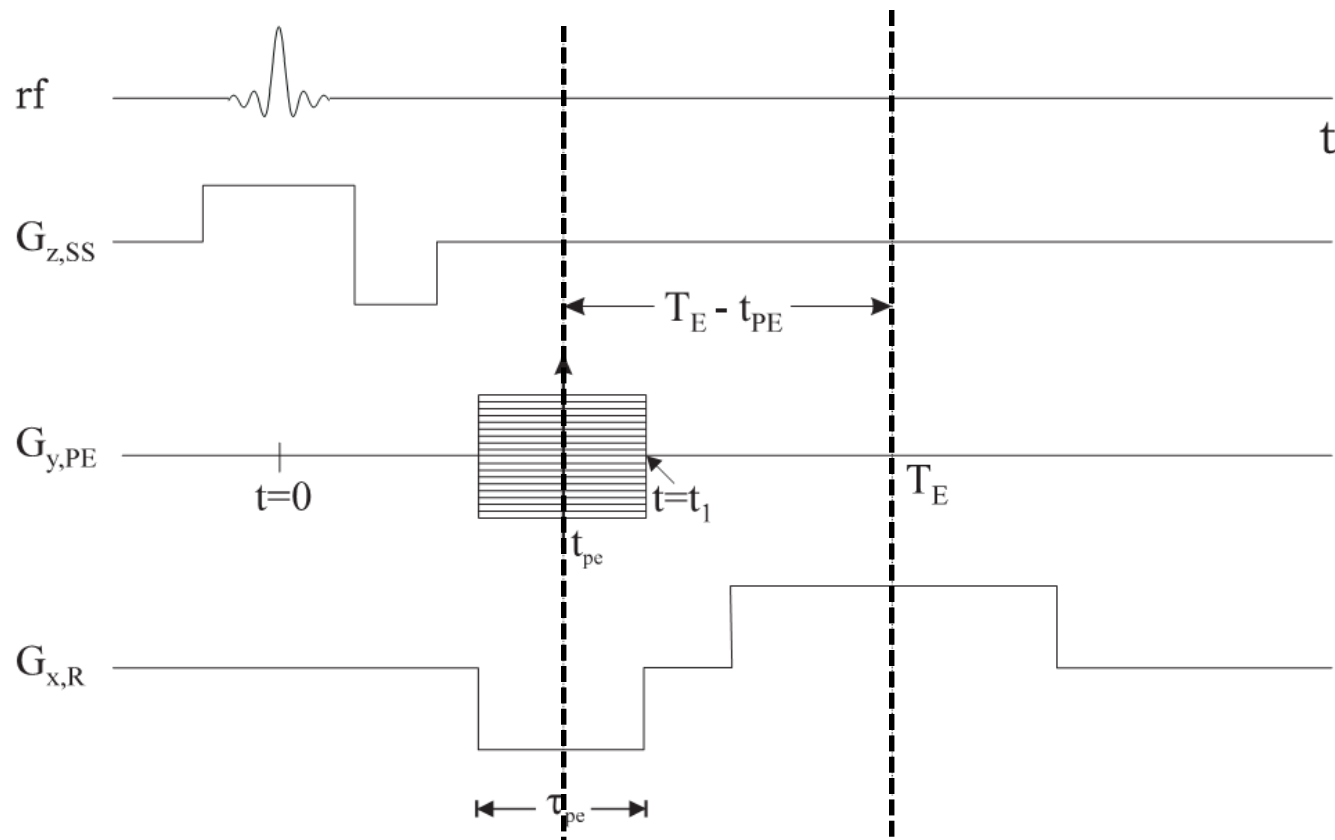
$$G_2 = -2G$$





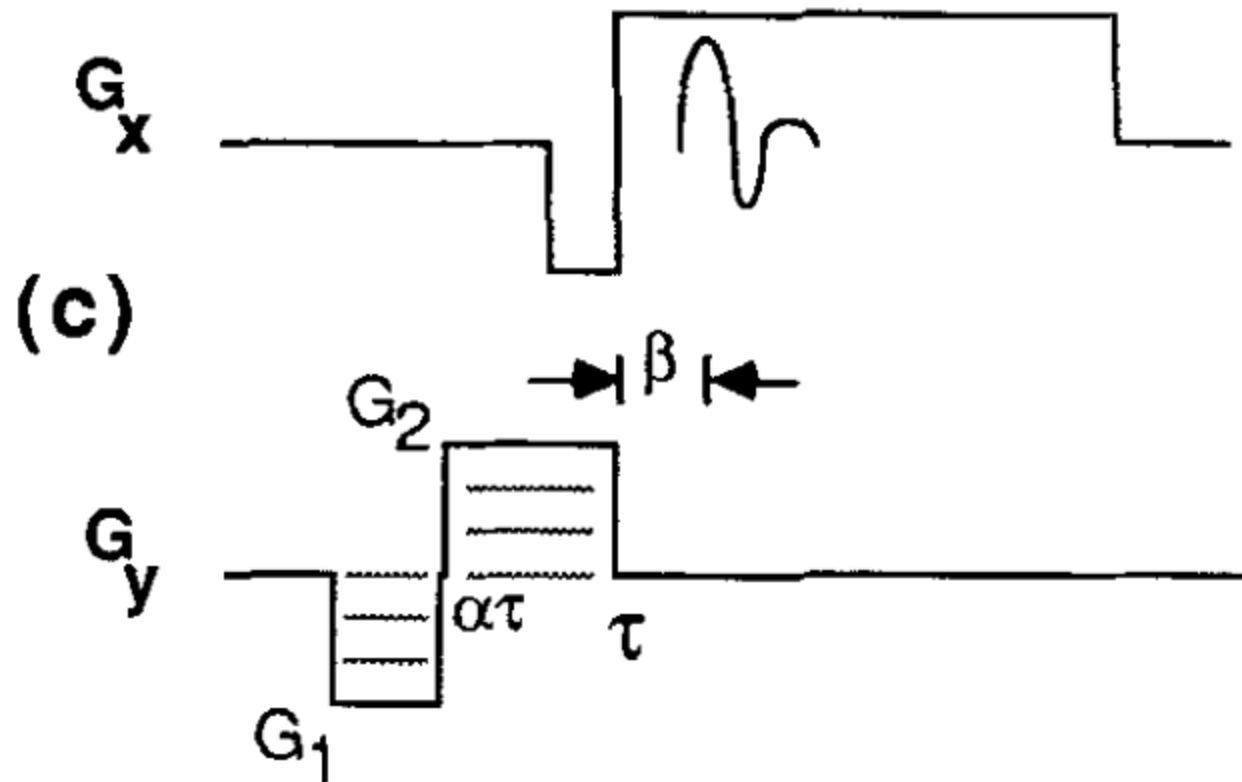
Flow Compensation in Slice Select Direction





Phase encoding
Direction

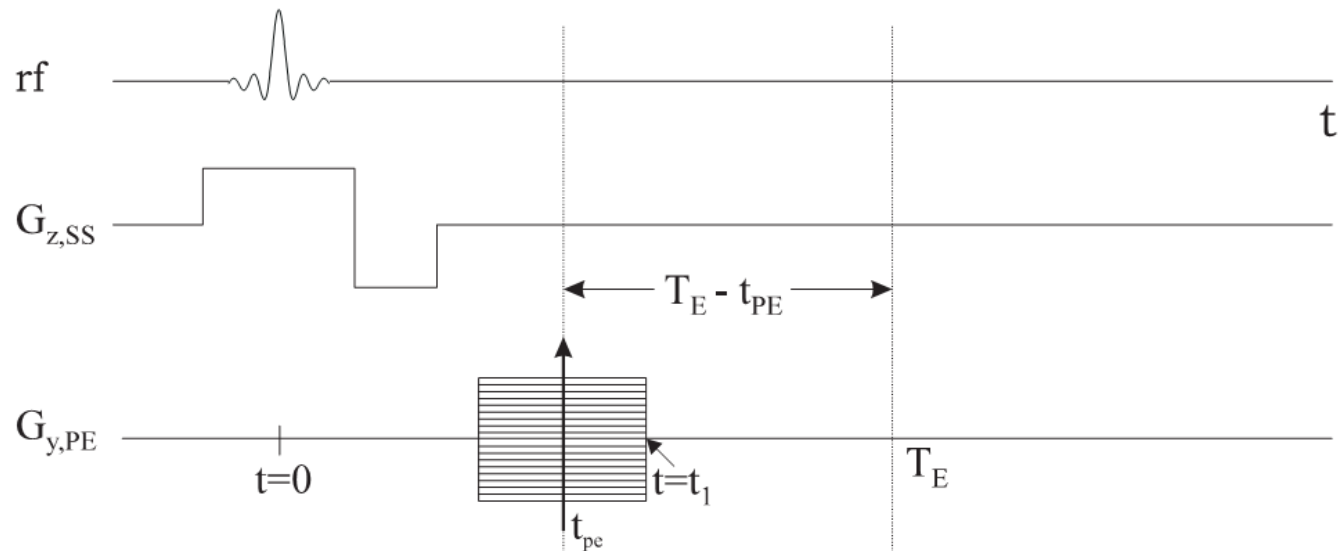
$$M_1(t_1) = \frac{G_y}{2} (2\tau_{pe}t'_1 - \tau_{pe}^2)$$



$$\phi = \gamma G_y (y_0 + v_y TE) \tau.$$

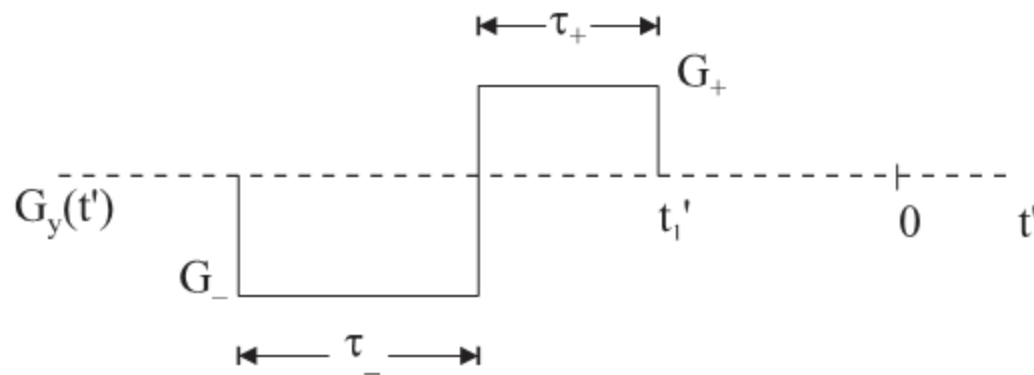
$$G_1 \alpha \tau + G_2 (1 - \alpha) \tau = G_y \tau$$

$$G_1 \alpha^2 \frac{\tau^2}{2} + G_2 (1 - \alpha^2) \frac{\tau^2}{2} = G_y \tau TE$$



$$M_1(t_1) = \frac{G_y}{2} \left(2\tau_{pe}t'_1 - \tau_{pe}^2 \right)$$

$$\begin{aligned} \phi_v(t_1) &= -\gamma v_y G_y \tau_{pe} \left(t'_1 - \frac{\tau_{pe}}{2} \right) \\ &= -2\pi k_y \left[v_y \left(t'_1 - \frac{\tau_{pe}}{2} \right) \right] \\ &\equiv -2\pi k_y \Delta y_v \end{aligned}$$



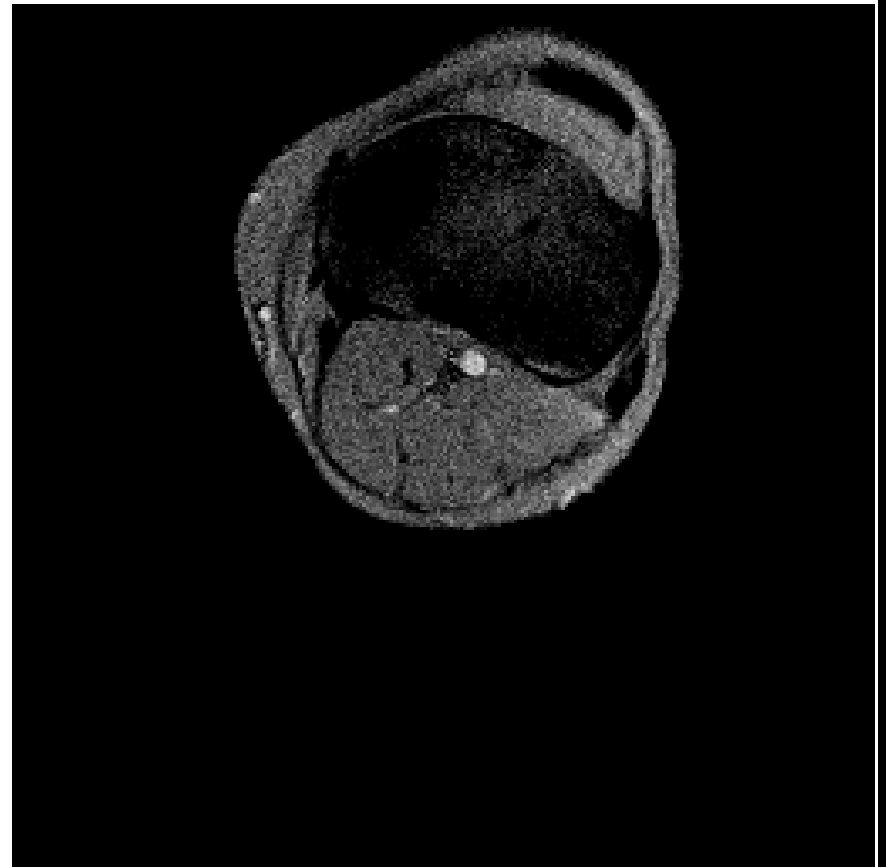
$$M_0(0) \equiv \int_{-\infty}^0 \Delta G_y(t) dt = \frac{1}{\gamma L_y}$$

$$M_1(0) \equiv \int_{-\infty}^0 t \Delta G_y(t) dt = 0$$

Examples



Uncompensated
signal loss and Ghosting
(due to pulsatile flow)



Compensated

$$x(t') = x + \alpha \sin(\omega_m t')$$

$$\begin{aligned} t' &= (G_y/\Delta G + n_y)T_R \\ &= (k_y/\Delta k_y + n_y)T_R \end{aligned}$$

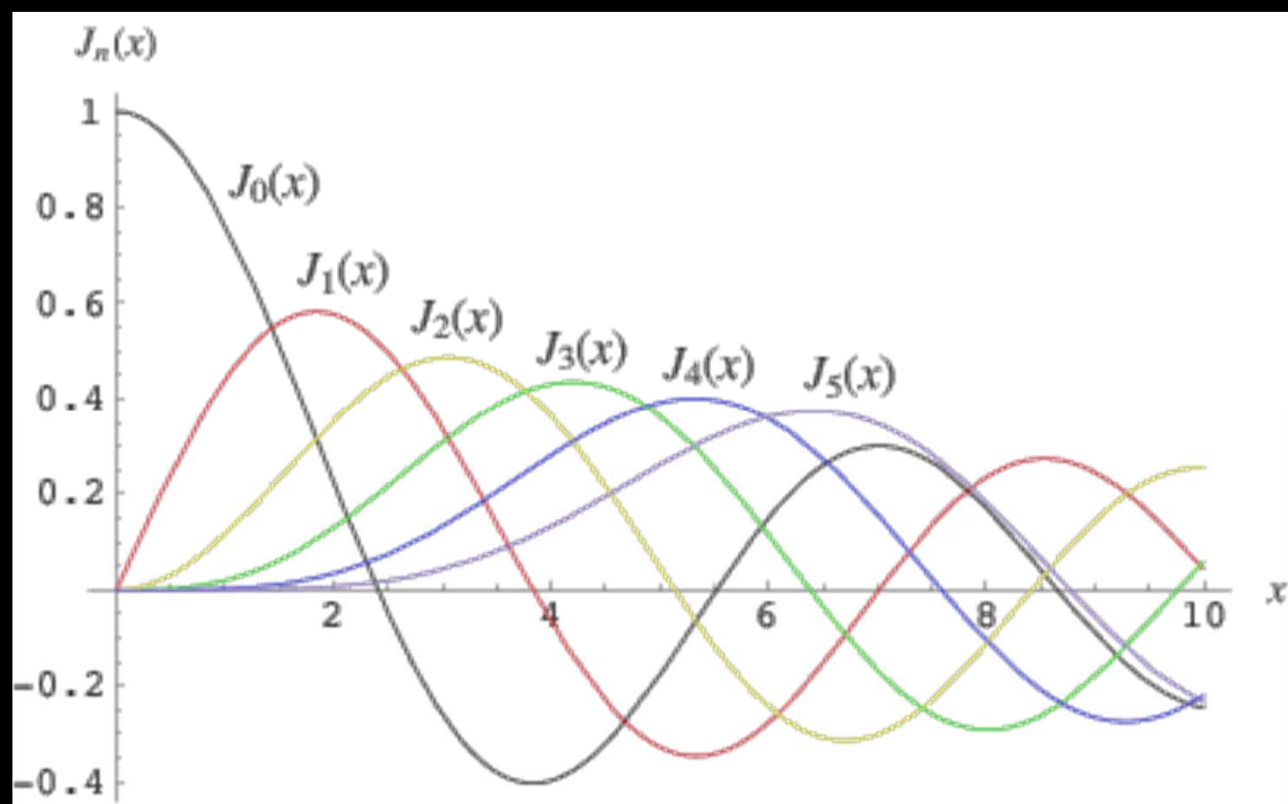
$$s(k_x, k_y) = \int \int dx dy \rho(x(t'), y) e^{-i2\pi(k_x x(t') + k_y y)}$$

$$x' = x - \alpha \sin \omega_m t'$$

$$s(k_x, k_y) = \int \int dx' dy \rho(x', y) e^{-i2\pi k_x (x' + \alpha \sin(\omega_m t'))} e^{-i2\pi k_y y}$$

$$\begin{aligned}
 j_0(x) &= \frac{\sin x}{x} \\
 j_1(x) &= \frac{\sin x}{x^2} - \frac{\cos x}{x} \\
 j_2(x) &= \left(\frac{3}{x^2} - 1\right) \frac{\sin x}{x} - \frac{3 \cos x}{x^2} \\
 j_3(x) &= \left(\frac{15}{x^3} - \frac{6}{x}\right) \frac{\sin x}{x} - \left(\frac{15}{x^2} - 1\right) \frac{\cos x}{x},
 \end{aligned}$$

$$\exp \{-(ia \sin \omega_m t')\} = \sum_{p=-\infty}^{\infty} J_p(a) e^{-ip\omega_m t'}$$



position changing every TR in a periodic manner.

$$x(TR) = x' + \alpha \sin\left(\omega \left(\frac{k_y}{2k_y}\right) TR\right)$$

$$S(k_x, k_y) = \iint dx dy \rho(x', y) e^{-j2\pi k_x (x' + \alpha \sin(\frac{\omega k_y}{2k_y} TR))} e^{-j2\pi k_y y}$$

$$S(k_x, k_y) = \iint dx' dy \rho(x', y) e^{-j2\pi k_x x'} e^{-j2\pi k_y y} e^{-j2\pi k_x \alpha \sin(\frac{\omega k_y}{2k_y} TR)}$$

with $A = 2\pi k_x \alpha$

$$e^{-jA \sin(\frac{\omega k_y}{2k_y} TR)} = \sum_{p=-\infty}^{\infty} J_p(A) e^{-j p \frac{\omega k_y TR}{2k_y}}$$

$$S(k_x, k_y) = \sum_{p=-\infty}^{\infty} \iint dx' dy \rho(x', y) J_p(2\pi k_x \alpha) e^{-j2\pi (k_x x' + k_y y)} e^{-j p \frac{\omega k_y TR}{2k_y}}$$

$$\Delta y(p) = \left[p \left(\frac{T_R}{T} \right) L_y \right] \text{ modulo } L_y$$

Spin density changing every TR

$$\underline{\rho(x, y, TR) = \rho_0(x, y) + \alpha \sin\left(\frac{\omega K_y TR}{\Delta K_y}\right)}$$

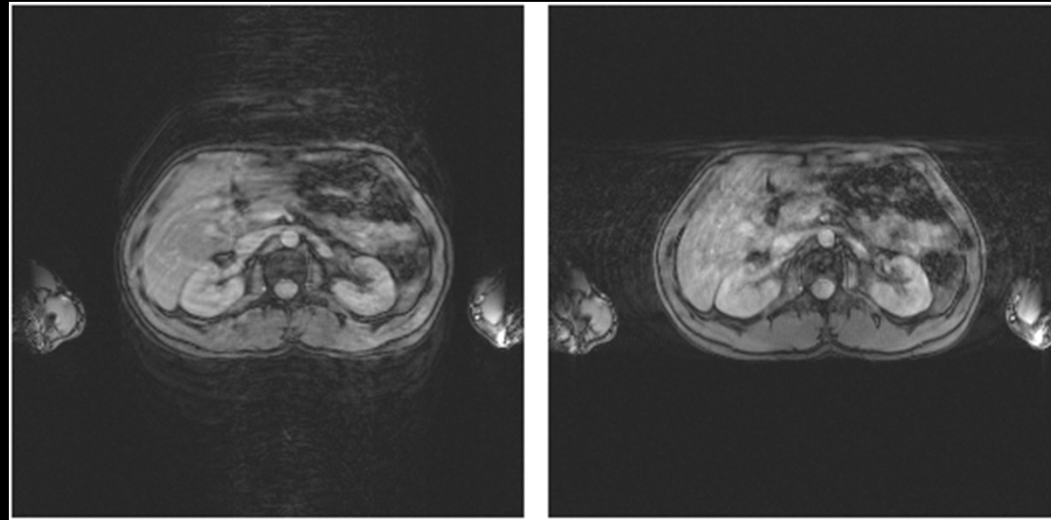
$$S(k_x, k_y) = \iint dx dy \left[\rho_0(x, y) + \alpha \sin\left(\frac{\omega K_y TR}{\Delta K_y}\right) \right] e^{-j2\pi(k_x x + k_y y)}$$

$$S(k_x, k_y) = \alpha \sin\left(\frac{\omega K_y TR}{\Delta K_y}\right) \iint dx dy e^{-j2\pi(k_x x + k_y y)} + \iint dx dy \rho_0(x, y) e^{-j2\pi(k_x x + k_y y)}$$

Respiratory motion

- Assume $x(t') = x_0 + \alpha \sin(\omega t')$, where $\omega = 2\pi/T$. T is the period of the motion.
- $t' = (G_y/\Delta G + n_y) T_R = (k_y/\Delta k_y + n_y) T_R$
- Thus, the ghosting due to the respiratory motion only occurs along the phase encoding direction.
- Try to choose T_R to be multiples of T .
- However, this may not be possible. Thus, choose $n_{\text{acq}} T_R$ to be roughly T and average the images over n_{acq} . Blurring will occur.

Examples: minimizing ghosting

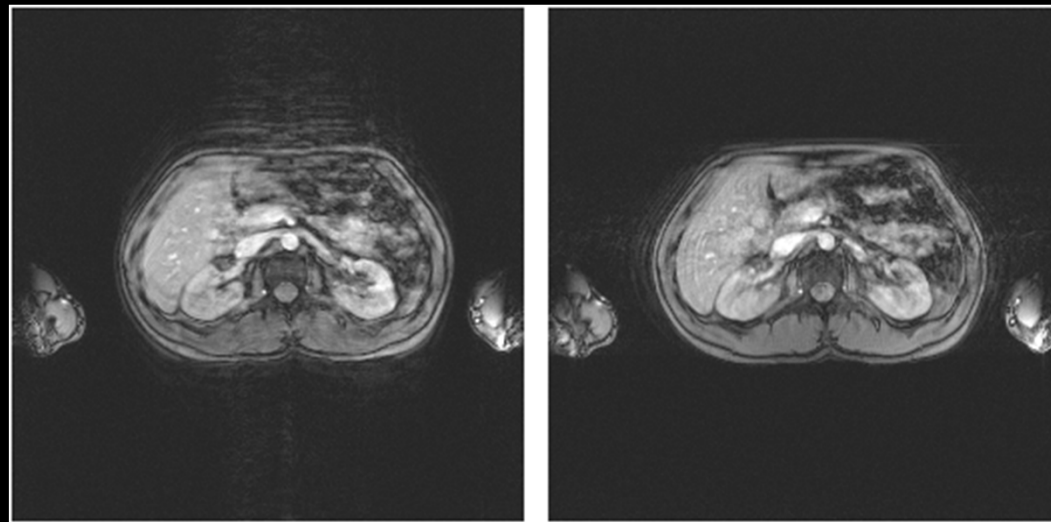


$T_R = 400 \text{ ms}$

Phase encoding

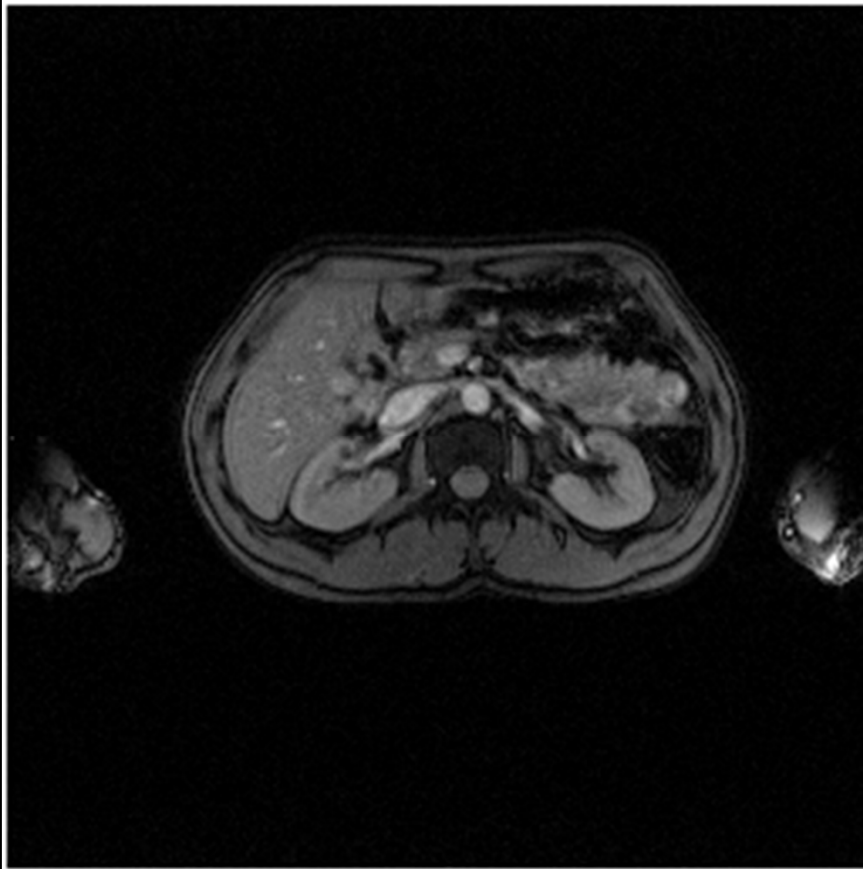


Read direction

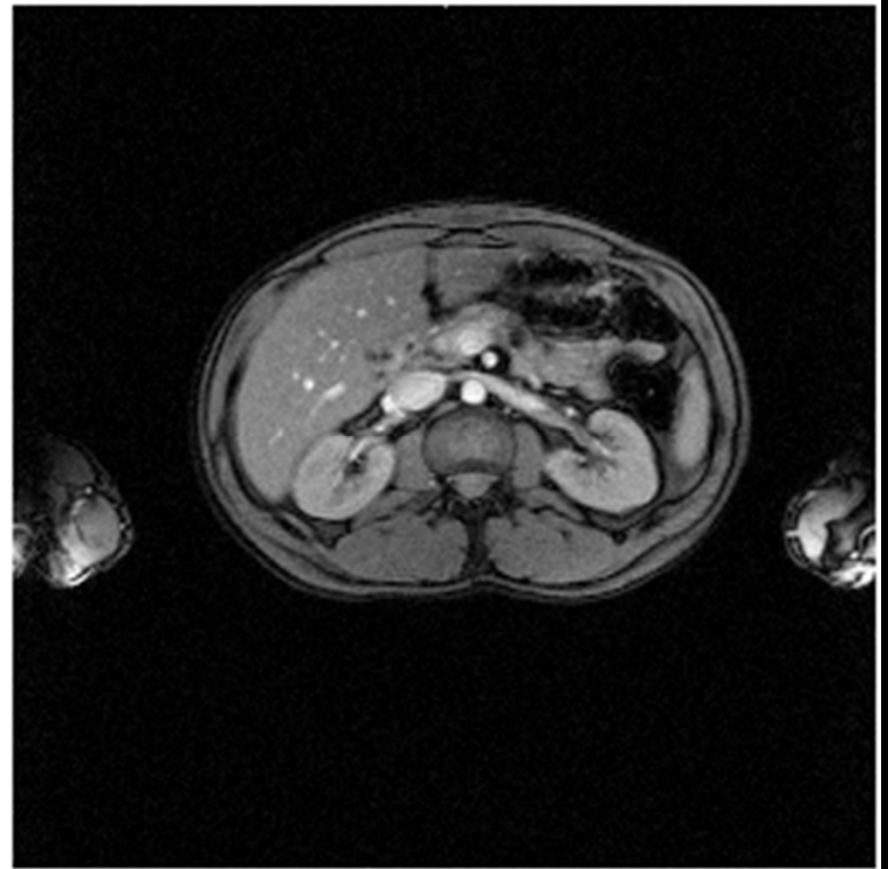


$T_R = 200 \text{ ms}$

Examples: eliminating ghosting



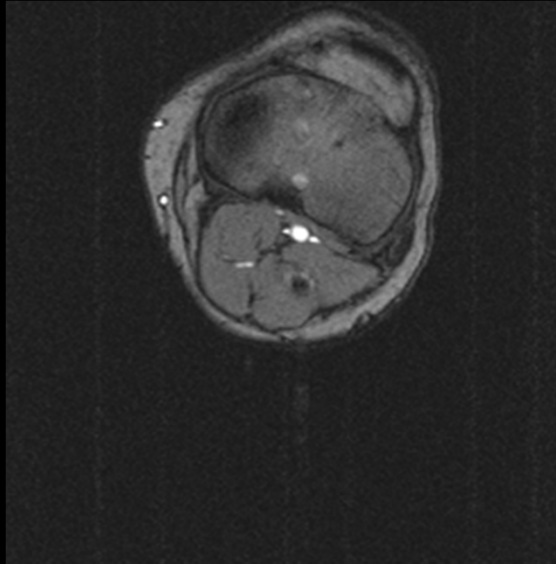
$T_R = 50 \text{ ms}$, $T \sim 4 \text{ sec.}$



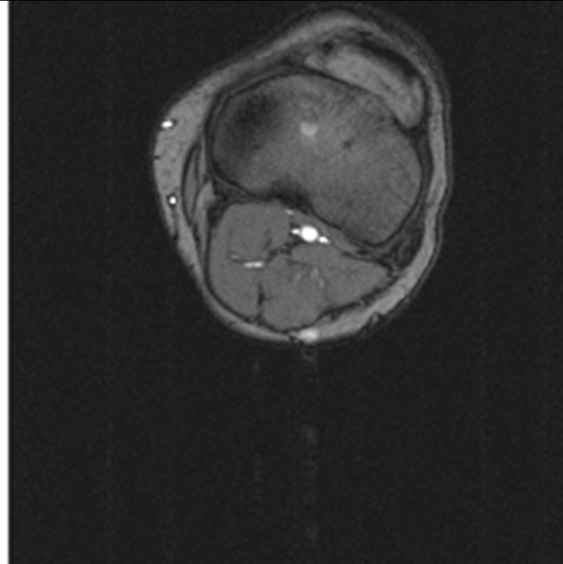
Breath-hold

Examples: pulsatile flow

$T_R = 14 \text{ ms},$
 $N_{\text{acq}} = 1.$

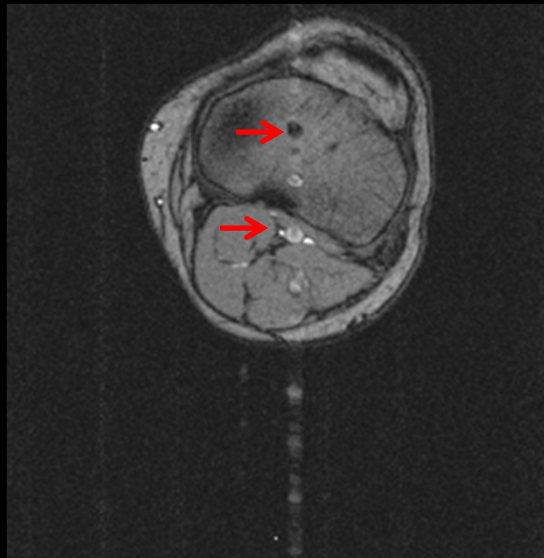


$T_R = 14 \text{ ms},$
 $N_{\text{acq}} = 2.$



similar!

$T_R = 14 \text{ ms},$
 $N_{\text{acq}} = 1.$



uncompensated

$T_R = 28 \text{ ms},$
 $N_{\text{acq}} = 1.$

